

# DP IB Maths: AI HL

## 4.13 Transition Matrices & Markov Chains

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## 4.13.1 Markov Chains

### Markov Chains

#### What is meant by a “state”?

- States refer to **mutually exclusive events** with the current event **able to change over time**
- Examples of states include:
  - Daily weather conditions
    - The states could be: “sunny” and “not sunny”
  - Countries visited by an inspector each day
    - The states could be: “France”, “Spain” and “Germany”
  - Store chosen for weekly grocery shop:
    - The states could be: “Foods-U-Like”, “Smiley Shoppers” and “Better Buys”

#### What is a Markov chain?

- A **Markov chain** is a model that describes a **sequence of states** over a period of time
  - Time is measured in discrete steps
    - Such as days, months, years, etc
- The **conditions** for a Markov chain are:
  - The **probability** of a state being the **next state** in the sequence **only depends** on the **current state**
    - For example  
The 11<sup>th</sup> state **only depends** on the 10<sup>th</sup> state  
The first 9 states **do not affect** the 11<sup>th</sup> state
    - This probability is called a **transition probability**
  - The **transition probabilities do not change** over time
    - For example  
The probability that the 11<sup>th</sup> state is A given that the 10<sup>th</sup> state is B is equal to the probability that the 12<sup>th</sup> state is A given that the 11<sup>th</sup> state is B
- A Markov chain is said to be **regular** if there is a value  $k$  such that in **exactly  $k$  steps** it is possible to reach any state regardless of the initial state
  - The chain where A can only go to B, B can only go to C and C can only go to A, is **not regular**
    - After any number of changes, A can only go to either B or C but not both
    - After 100 changes, A can end up at B but not C
    - After 500 changes, A can end up at C but not B

#### What is a transition state diagram?

- A **transition diagram** is a **directed graph**
  - The **vertices** are the **states**
  - The **edges** represent the **transition probabilities** between the states
- The graph can contain
  - **Loops**
    - These will be the transition probabilities of the next state being the same as the current state

- **Two edges between each pair of vertices**
  - The edges will be in opposite directions
  - Each edge will show the transition probability of the state changing in the given direction
- The **probabilities** on the **edges coming out** of a vertex **add up to 1**

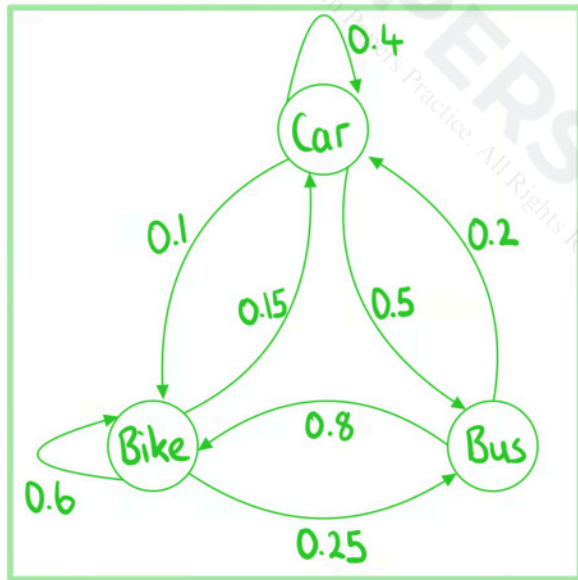
### Worked example

Fleur travels to work by car, bike or bus. Each day she chooses her mode of transport based on the transport she chose the previous day.

- If Fleur travels by car then there is a 40% chance that she will travel by car the following day and a 10% chance that she will travel by bike.
- If Fleur travels by bike then there is a 60% chance that she will travel by bike the following day and a 25% chance that she will travel by bus.
- If Fleur travels by bus then there is an 80% chance that she will travel by bike the following day and a 20% chance that she will travel by car.

Represent this information as a transition state diagram.

The probabilities on the arrows coming out of a state add to 1



## 4.13.2 Transition Matrices

### Transition Matrices

#### What is a transition matrix?

- A **transition matrix**  $T$  shows the **transition probabilities** between the current state and the next state
  - The **columns** represent the **current states**
  - The **rows** represent the **next states**
- The element of  $T$  in the  $i^{\text{th}}$  row and  $j^{\text{th}}$  column gives the transition probability  $t_{ij}$  of :
  - the **next state** being the state corresponding to **row  $i$**
  - **given that the current state** is the state corresponding to **column  $j$**
- The probabilities in each **column** must **add up to 1**
- The transition matrix depends on how you assign the states to the columns
  - Each transition matrix for a Markov chain will contain the same elements
    - The rows and columns may be in different orders though
    - E.g. Sunny (S) & Cloudy (C) could be in the order **S then C** or **C then S**

#### What is an initial state probability matrix?

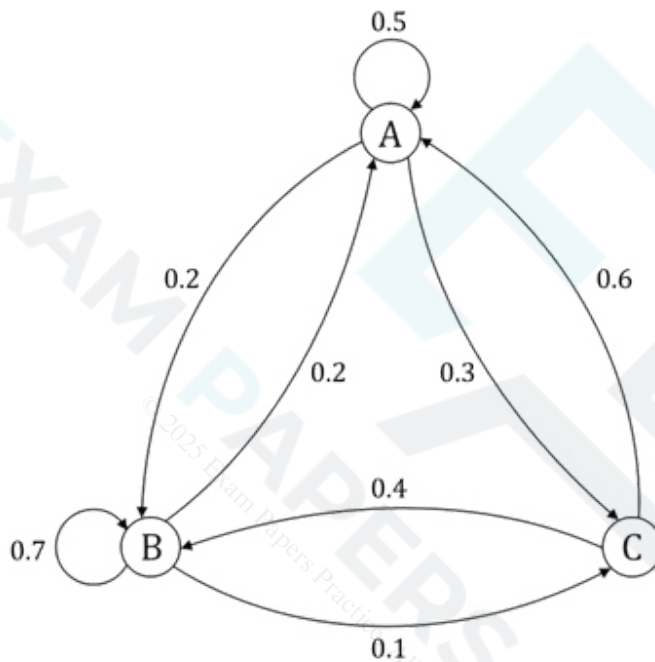
- An **initial state probability matrix**  $s_0$  is a column vector which contains the **probabilities** of each state being chosen as the **initial state**
  - If you know which state was chosen as the initial state then that entry will be 1 and the others will all be zero
- You can find the **state probability matrix**  $s_1$  which contains the probabilities of each state being chosen after **one interval of time**
  - $s_1 = Ts_0$

#### How do I find expected values after one interval of time?

- Suppose the Markov change represents a **population moving between states**
  - Examples include:
    - People in a town switching gyms each year
    - Children choosing a type of sandwich for their lunch each day
- Suppose the **total population is fixed** and equals  $N$
- You can **multiply the state probability matrix**  $s_1$  by  $N$  to find the expected number of members of the population at each state

### Worked example

Each year Jamie donates to one of three charities: A, B or C. At the start of each year, the probabilities of Jamie continuing donate to the same charity or changing charities are represented by the following transition state diagram:



- a) Write down a transition matrix  $T$  for this system of probabilities.

Current state

Next state

A B C

A 0.5 0.2 0.6

B 0.2 0.7 0.4

C 0.3 0.1 0

$$T = \begin{pmatrix} 0.5 & 0.2 & 0.6 \\ 0.2 & 0.7 & 0.4 \\ 0.3 & 0.1 & 0 \end{pmatrix}$$

- b) There is a 10% chance that charity A is the first charity that Jamie chooses, a 10% chance for charity B and an 80% chance for charity C. Find the charity which has the highest probability of being picked as the second charity after the first year.

Write down the initial state vector  $s_0 = \begin{pmatrix} 0.1 \\ 0.1 \\ 0.8 \end{pmatrix}$

$$s_1 = Ts_0 \quad s_1 = \begin{pmatrix} 0.5 & 0.2 & 0.6 \\ 0.2 & 0.7 & 0.4 \\ 0.3 & 0.1 & 0 \end{pmatrix} \begin{pmatrix} 0.1 \\ 0.1 \\ 0.8 \end{pmatrix} = \begin{pmatrix} 0.55 \\ 0.41 \\ 0.04 \end{pmatrix}$$

Charity A has the highest probability of being the second charity picked.

## Powers of Transition Matrices

### How do I find powers of a transition matrix?

- You can simply use your **GDC** to find given powers of a matrix
- The power could be left in terms of an **unknown**  $n$ 
  - In this case it would be more helpful to write the transition matrix in diagonalised form (see section **1.8.2 Applications of Matrices**)  $T = PDP^{-1}$  where
    - $D$  is a **diagonal matrix** of the **eigenvalues**
    - $P$  is a matrix of **corresponding eigenvectors**
  - Then  $T^n = PD^nP^{-1}$ 
    - This is given in the **formula booklet**
  - Every transition matrix always has an **eigenvalue equal to 1**

### What is represented by the powers of a transition matrix?

- The powers of a transition matrix also **represent probabilities**
- The element of  $T^n$  in the  $i^{\text{th}}$  row and  $j^{\text{th}}$  column gives the **probability**  $t_{ij}^n$  of :
  - the **future state** after  **$n$  intervals of time** being the state corresponding to **row  $i$**
  - given that** the **current state** is the state corresponding to **column  $j$**
- For example: Let  $T$  be a transition matrix with the element  $t_{2,3}$  representing the probability that tomorrow is sunny given that it is raining today
  - The element  $t_{2,3}^5$  of the matrix  $T^5$  represents the probability that it is sunny in 5 days' time given that it is raining today
- The probabilities in **each column** must still **add up to 1**

### How do I find the column state matrices?

- The column state matrix  $s_n$  is a column vector which contains the **probabilities** of each state being chosen after  $n$  intervals of time given the current state
  - $s_n$  depends on  $s_0$
- To calculate the column state matrix you raise the transition matrix to the power  $n$  and multiply by the initial state matrix
  - $T^n s_0 = s_n$ 
    - You are given this in the **formula booklet**
- You can multiply  $s_n$  by the fixed population size to find the expected number of members of the population at each state after  $n$  intervals of time

### Worked example

At a cat sanctuary there are 1000 cats. If a cat is brushed on a given day, then the probability it is brushed the following day is 0.2. If a cat is not brushed on a given day, then the probability that it will be brushed the following day is 0.9.

The transition matrix  $T$  is used to model this information with  $T = \begin{pmatrix} 0.2 & 0.9 \\ 0.8 & 0.1 \end{pmatrix}$ .

- a) On Monday Hippo the cat is brushed. Find the probability that Hippo will be brushed on Friday.

Identify the states with the rows/columns

$$\begin{array}{c}
 \text{Current} \\
 \begin{array}{cc}
 & \begin{matrix} B & B' \end{matrix} \\
 \begin{matrix} \text{Next} \\ B \\ B' \end{matrix} & \begin{pmatrix} 0.2 & 0.9 \\ 0.8 & 0.1 \end{pmatrix}
 \end{array}
 \end{array}$$

Friday is 4 days after Monday

$$T^4 = \begin{pmatrix} 0.2 & 0.9 \\ 0.8 & 0.1 \end{pmatrix}^4 = \begin{pmatrix} 0.6424 & 0.4023 \\ 0.3576 & 0.5977 \end{pmatrix} \begin{array}{c} B \\ B' \end{array} \left. \vphantom{\begin{pmatrix} 0.6424 & 0.4023 \\ 0.3576 & 0.5977 \end{pmatrix}} \right\} \begin{array}{c} \text{Future} \\ \end{array}$$

$\underbrace{\begin{array}{cc} B & B' \end{array}}_{\text{Current}}$

Current = B  
Future = B

0.6424

- b) On Monday 700 cats were brushed. Find the expected number of cats that will be brushed on the following Monday.



On Monday 700 brushed  $s_0 = \begin{pmatrix} 0.7 \\ 0.3 \end{pmatrix}$

Expected numbers after 7 days

$$\text{Total} \times S_7 = \text{Total} \times T^7 s_0$$

$$1000 \times \begin{pmatrix} 0.2 & 0.9 \\ 0.8 & 0.1 \end{pmatrix}^7 \begin{pmatrix} 0.7 \\ 0.3 \end{pmatrix} = \begin{pmatrix} 0.2 & 0.9 \\ 0.8 & 0.1 \end{pmatrix}^7 \begin{pmatrix} 700 \\ 300 \end{pmatrix} = \begin{pmatrix} 515.36309 \\ 484.63691 \end{pmatrix} \begin{matrix} B \\ B' \end{matrix}$$

515 cats

## Steady State & Long-term Probabilities

### What is the steady state of a regular Markov chain?

- The vector  $\mathbf{s}$  is said to be a **steady state** vector if it does not change when multiplied by the transition matrix
  - $T\mathbf{s} = \mathbf{s}$
- **Regular Markov chains** have steady states
  - A Markov chain is said to be regular if there exists a **positive integer  $k$**  such that **none of the entries are equal to 0** in the matrix  $T^k$ 
    - For this course all Markov chains will be regular
- The transition matrix for a regular Markov chain will have **exactly one** eigenvalue equal to 1 and the **rest will all be less than 1**
- As  $n$  gets bigger  $T^n$  tends to a matrix where **each column is identical**
  - The column matrix formed by using **one of these columns** is called the steady state column matrix  $\mathbf{s}$
  - This means that the **long-term probabilities** tend to fixed probabilities
    - $\mathbf{s}_n$  tends to  $\mathbf{s}$

### How do I use long-term probabilities to find the steady state?

- As  $T^n$  tends to a matrix whose columns equal the steady state vector
  - Calculate  $T^n$  for a large value of  $n$  using your GDC
  - If the columns are identical when rounded to a required degree of accuracy then the column is the steady state vector
  - If the columns are not identical then choose a higher power and repeat

### How do I find the exact steady state probabilities?

- As  $T\mathbf{s} = \mathbf{s}$  the steady state vector  $\mathbf{s}$  is the **eigenvector** of  $T$  corresponding to the **eigenvalue equal to 1** whose elements sum to 1:
  - Let  $\mathbf{s}$  have entries  $x_1, x_2, \dots, x_n$
  - Use  $T\mathbf{s} = \mathbf{s}$  to form a system of linear equations
  - There will be an infinite number of solutions so choose a value for one of the unknowns
    - For example: let  $x_n = 1$
  - Ignoring the last equation solve the system of linear equations to find  $x_1, x_2, \dots, x_{n-1}$
  - Divide each value  $x_i$  by the sum of the values
    - This makes the values add up to 1
- You might be asked to **show this result using diagonalisation**
  - Write  $T = PDP^{-1}$  where  $D$  is the diagonal matrix of eigenvalues and  $P$  is the matrix of eigenvectors
  - Use  $T^n = PD^nP^{-1}$
  - As  $n$  gets large  $D^n$  tends to a matrix where all entries are 0 apart from one entry of 1 due to the eigenvalue of 1
  - Calculate the limit of  $T^n$  which will have **identical columns**
    - You can calculate this by multiplying the three matrices  $(P, D^\infty, P^{-1})$  together

### ✎ Worked example

If a cat is brushed on a given day, then the probability it is brushed the following day is 0.2. If a cat is not brushed on a given day, then the probability that it will be brushed the following day is 0.9.

The transition matrix  $T$  is used to model this information with  $T = \begin{pmatrix} 0.2 & 0.9 \\ 0.8 & 0.1 \end{pmatrix}$ .

- a) Find an eigenvector of  $T$  corresponding to the eigenvalue 1.

$\underline{v}$  is an eigenvector of  $T$  with eigenvalue 1 if  $T\underline{v} = \underline{v}$

Let  $\underline{v} = \begin{pmatrix} x_1 \\ x_2 \end{pmatrix}$

$$T\underline{v} = \begin{pmatrix} 0.2 & 0.9 \\ 0.8 & 0.1 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} 0.2x_1 + 0.9x_2 \\ 0.8x_1 + 0.1x_2 \end{pmatrix}$$

$$T\underline{v} = \underline{v} \quad 0.2x_1 + 0.9x_2 = x_1 \Rightarrow 0.9x_2 = 0.8x_1 \Rightarrow 9x_2 = 8x_1$$

$$0.8x_1 + 0.1x_2 = x_2 \Rightarrow 0.8x_1 = 0.9x_2 \Rightarrow 8x_1 = 9x_2$$

Find a solution  $x_1 = 9$  and  $x_2 = 8$

$\begin{pmatrix} 9 \\ 8 \end{pmatrix}$  or any scalar multiple

- b) Hence find the steady state vector.

Scale the elements so that they add to 1  $\begin{pmatrix} 9 \\ 17 \\ 8 \\ 17 \end{pmatrix}$

The eigenvector corresponding to the eigenvalue 1, whose elements add to 1, is the steady state vector.

$$\begin{pmatrix} \frac{9}{17} \\ \frac{8}{17} \end{pmatrix}$$