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# 4.1 Scalars & Vectors



# **PHYSICS**

# **AQA A Level Revision Notes**



#### 4.1 Scalars & Vectors

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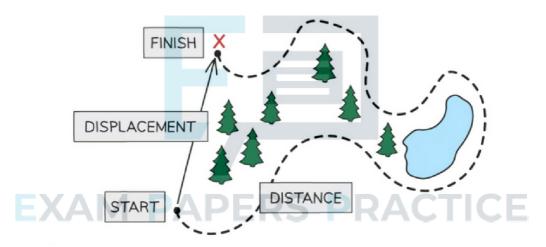




#### 4.1.1 Scalars & Vectors

#### Scalars & Vectors

- · A scalar is a quantity which only has a magnitude (size)
- · A vector is a quantity which has both a magnitude and a direction
- For example, if a person goes on a hike in the woods to a location which is a couple of miles
  from their starting point
  - As the crow flies, their displacement will only be a few miles but the distance they walked will be much longer



#### Displacement is a vector while distance is a scalar quantity

- Distance is a scalar quantity because it describes how far an object has travelled overall, but not the direction it has travelled in
- **Displacement** is a vector quantity because it describes how far an object is from where it started and in what direction
- Some common scalar and vector quantities are shown in the table below:



#### Scalars and Vectors Table

SCALARS	VECTORS
DISTANCE	DISPLACEMENT
SPEED	VELOCITY
MASS	ACCELERATION
TIME	FORCE
ENERGY	MOMENTUM
VOLUME	
DENSITY	
PRESSURE	
ELECTRIC CHARGE	
TEMPERATURE DERS	PRACTIC



# Exam Tip

Do you have trouble figuring out if a quantity is a vector or a scalar? Just think - can this quantity have a minus sign? For example - can you have negative energy? No. Can you have negative displacement? Yes!

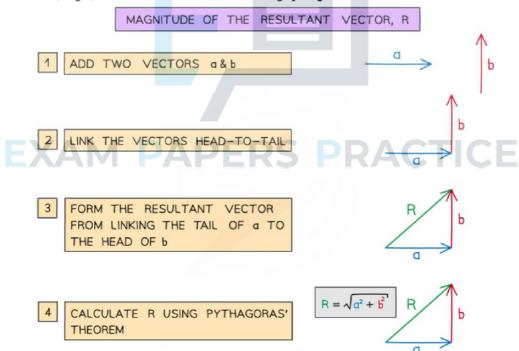


## **Combining Vectors**

- Vectors are represented by an arrow
  - The arrowhead indicates the direction of the vector
  - The length of the arrow represents the magnitude
- · Vectors can be combined by adding them to produce the resultant vector
  - The resultant vector is sometimes known as the 'net' vector (eg. the net force)
- . There are two methods that can be used to add vectors
  - Calculation if the vectors are perpendicular
  - · Scale drawing if the vectors are not perpendicular

#### Vector Calculation

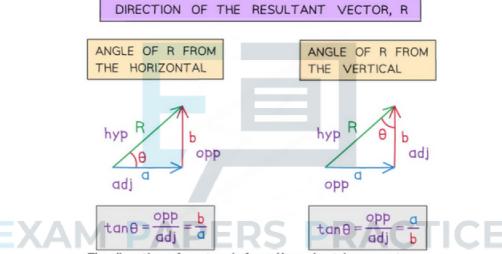
- · Vector calculations will be limited to two vectors at right angles
- This means the combined vectors produce a right-angled triangle and the magnitude (length) of the resultant vector is found using Pythagoras' theorem



 $The \, magnitude \, of \, the \, resultant \, vector \, is \, found \, by \, using \, Pythagoras \, {}' \, Theorem \, In the experimental experiments and the experimental e$ 



- The direction of the resultant vector is found from the angle it makes with the horizontal or vertical
  - The question should imply which angle it is referring to (ie. Calculate the angle from the x-axis)
- Calculating the angle of this resultant vector from the horizontal or vertical can be done
  using trigonometry
  - Either the sine, cosine or tangent formula can be used depending on which vector magnitudes are calculated

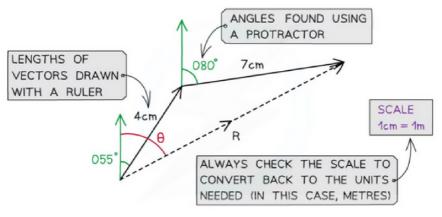


The direction of vectors is found by using trigonometry

### Scale Drawing

- When two vectors are not at right angles, the resultant vector can be calculated using a scale drawing
  - Step 1: Link the vectors head-to-tail if they aren't already
  - Step 2: Draw the resultant vector using the triangle or parallelogram method
  - Step 3: Measure the length of the resultant vector using a ruler
  - Step 4: Measure the angle of the resultant vector (from North if it is a bearing) using a protractor





# A scale drawing of two vector additions. The magnitude of resultant vector R is found using a rule and its direction is found using a protractor

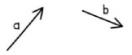
- Note that with scale drawings, a scale may be given for the diagram such as 1 cm = 1 km since only limited lengths can be measured using a ruler
- . The final answer is always converted back to the units needed in the diagram
  - Eg. For a scale of 1cm = 2 km, a resultant vector with a length of 5 cm measured on your ruler is actually 10 km in the scenario
- There are two methods that can be used to combine vectors: the **triangle method** and the **parallelogram method**
- · To combine vectors using the triangle method:
  - Step 1: link the vectors head-to-tail.
  - Step 2: the resultant vector is formed by connecting the tail of the first vector to the head of the second vector
- · To combine vectors using the parallelogram method:
  - Step 1: link the vectors tail-to-tail
  - · Step 2: complete the resulting parallelogram
  - o Step 3: the resultant vector is the diagonal of the parallelogram

#### Vector Addition



Draw the vector c = a + b





TRIANGLE METHOD

STEP 1: LINK THE VECTORS HEAD-TO-TAIL

STEP 2: FORM THE RESULTANT VECTOR FROM LINKING THE TAIL OF a TO THE HEAD OF b

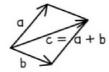


STEP 1: LINK THE VECTORS
TAIL-TO-TAIL

STEP 2: COMPLETE THE RESULTING PARALLELOGRAM



STEP 3: THE RESULTANT VECTOR
IS THE DIAGONAL OF THE PARALLELOGRAM



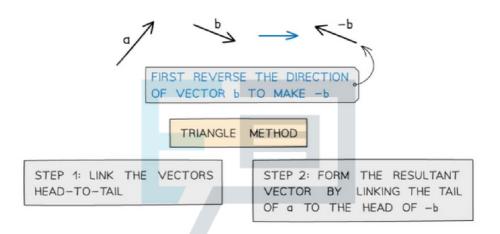
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### Vector Subtraction



Draw the vector c = a - b





PARALLELOGRAM METHOD

STEP 1: LINK THE VECTORS TAIL-TO-TAIL

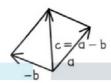
STEP 2: COMPLETE THE RESULTING PARALLELOGRAM







STEP 3: THE RESULTANT VECTOR IS THE DIAGONAL OF THE PARALLELOGRAM

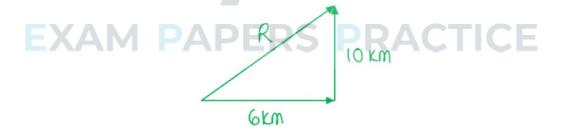


# ?

### Worked Example

A hiker walks a distance of 6 km due east and 10 km due north. Calculate the magnitude of their displacement and its direction from the horizontal

Step 1: Draw a vector diagram

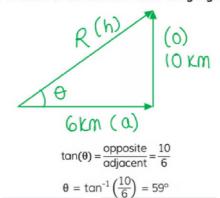


Step 2: Calculate the magnitude of the resultant vector using Pythagoras' Theorem

$$R = \sqrt{6^2 + 10^2}$$



Step 3: Calculate the direction of the resultant vector using trigonometry





## Exam Tip

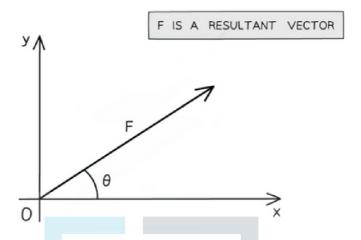
Pythagoras' Theorem and trigonometry are consistently used in vector addition, so make sure you're fully confident with the maths here!

4.1.2 Resolving Vectors

# Resolving Vectors RACTIC

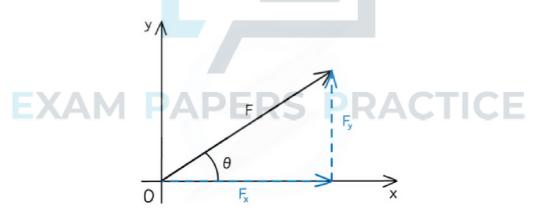
- · Two vectors can be represented by a single resultant vector
  - $\circ \ \ \text{Resolving a vector is the opposite of adding vectors}$
- · A single resultant vector can be resolved
  - This means it can be represented by two vectors, which in combination have the same effect as the original one
- When a single resultant vector is broken down into its parts, those parts are called components
- For example, a force vector of magnitude F and an angle of  $\theta$  to the horizontal is shown below





The resultant force F at an angle θ to the horizontal

 It is possible to resolve this vector into its horizontal and vertical components using trigonometry



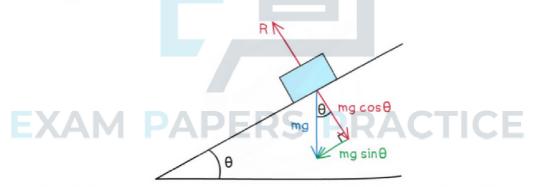


#### The resultant force F can be split into its horizontal and vertical components

- For the horizontal component, F<sub>x</sub> = F cos θ
- For the vertical component,  $F_v = F \sin \theta$

#### Forces on an Inclined Plane

- Objects on an inclined plane is a common scenario in which vectors need to be resolved
  - An inclined plane, or a slope, is a flat surface tilted at an angle, θ
- Instead of thinking of the component of the forces as horizontal and vertical, it is easier to think of them as parallel or perpendicular to the slope
- The weight of the object is vertically downwards and the normal (or reaction) force, R is always vertically up from the object
- The weight Wis a vector and can be split into the following components:
  - W cos (θ) perpendicular to the slope
  - Wsin (θ) parallel to the slope
- If there is no friction, the force W sin (θ) causes the object to move down the slope
- The object is not moving perpendicular to the slope, therefore, the normal force R = W cos
   (θ)

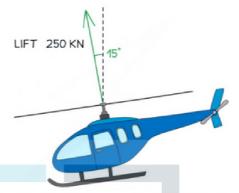


The weight vector of an object on an inclined plane can be split into its components parallel and perpendicular to the slope



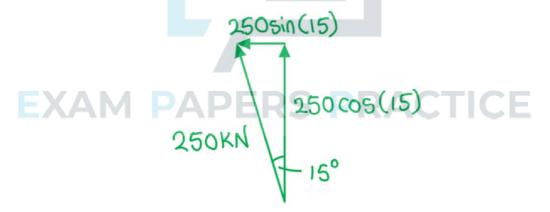
# Worked Example

A helicopter provides a lift of 250 kN when the blades are tilted at 15° from the vertical.



Calculate the horizontal and vertical components of the lift force.

Step 1: Draw a vector triangle of the resolved forces



Step 2: Calculate the vertical component of the lift force

 $Vertical = 250 \times cos(15) = 242 \text{ kN}$ 

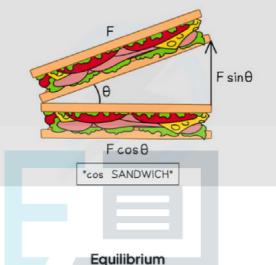
Step 3: Calculate the horizontal component of the lift force

Horizontal =  $250 \times \sin(15) = 64.7 \text{ kN}$ 



# Exam Tip

If you're unsure as to which component of the force is  $\cos\theta$  or  $\sin\theta$ , just remember that the  $\cos\theta$  is always the adjacent side of the right-angled triangle AKA, making a 'cos sandwich'

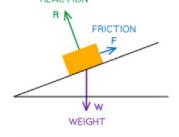


- · Coplanar forces can be represented by vector triangles
- · Forces are in equilibrium if an object is either
  - At rest
  - Moving at constant velocity
- In equilibrium, coplanar forces are represented by closed vector triangles
  - The vectors, when joined together, form a closed path
- · The most common forces on objects are
  - Weight
  - · Normal reaction force
  - o Tension (from cords and strings)
  - Friction
- The forces on a body in equilibrium are demonstrated below:



A VEHICLE IS AT REST ON A SLOPE AND HAS THREE FORCES ACTING ON IT TO KEEP IT IN EQUILIBRIUM

NORMAL REACTION







STEP 1: DRAW ALL THE FORCES ON THE FREE-BODY DIAGRAM STEP 2: REMOVE THE OBJECT AND PUT ALL THE FORCES COMING FROM A SINGLE POINT STEP 3:
REARRANGE THE FORCES
INTO A CLOSED VECTOR
TRIANGLE.
KEEP THE SAME LENGTH
AND DIRECTION

Three forces on an object in equilibrium form a closed vector triangle

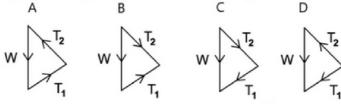
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# Worked Example

A weight hangs in equilibrium from a cable at point **X**. The tensions in the cables are  $T_1$  and  $T_2$  as shown.



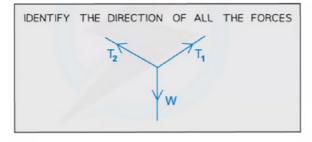
Which diagram correctly represents the forces acting at point  ${\bf X}$ ?



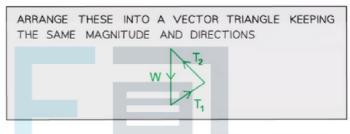


ANSWER: A

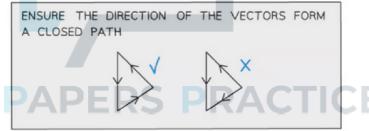
STEP 1



STEP 2



STEP 3



**EXAM** 



# Exam Tip

The diagrams in exam questions about this topic could ask you to draw to scale, so make sure you have a ruler handy!